



HOPPER AVE CORRIDOR FIRE RECOVERY IMPROVEMENTS- PSA APPROVAL

City Council Meeting
July 26, 2022

Chris Balanesi, Assistant Engineer
Grant Bailey, Supervising Engineer
Transportation & Public Works

BACKGROUND

- Hopper Ave Corridor – Coffey to Hwy 101 S
- Residential access to variety of uses
- 2017 Tubbs Fire destroyed homes & City-maintained landscape
- July 2021 Council Study Session on one-time monies
- February 2022 CC approved \$6M of PG&E Settlement Funds to project.

BACKGROUND

- Project scope not finalized, likely to include:
 - Pavement surface/reconstruction
 - Addition of median island
 - Vegetation restoration
 - Sidewalk rehabilitation & Creek Access
 - Bike & pedestrian improvements

ANALYSIS

- Request For Proposals issued 4/12
- 2 proposals received 5/10
- Solicitation, review and selection completed in accordance with City policy
- Evaluation determined Callander Associates Landscape Architecture, Inc. (CALA) most qualified

ANALYSIS

- CALA to provide:
 - Public Outreach & Engagement
 - Translation & Interpretation
 - Preliminary Design/Bridging Docs
 - Optional Environmental Review (as authorized by City only)

RECOMMENDATION

It is recommended by the Transportation and Public Works Department that the Council, by resolution, approve a Professional Services Agreement with Callander Associates Landscape Architecture, Inc. of Gold River, California, for public outreach and preliminary engineering/architectural design services associated with the Hopper Avenue Corridor Fire Recovery Improvements project, in an amount not to exceed \$466,764.00.

LOCATION MAP



Project Number: 2406

Hopper Ave Corridor Fire Recovery Improvements

Project Status: Planning

Project Areas (JL Keys labeled)

TPW

0 100 200 400 600 800 1,000 1,200 1,400 Feet City (2020) & County (2018) Aerials shown. Map Date: 6/13/2022

- Information and features shown on this map are intended for general location use only and may contain errors. Map produced by City of Santa Rosa, Asset Management Division. -

QUESTIONS?